

1 + 3 formalism

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Overview

- Part 1: General Relativity with a Linear Connection
- Part 2: 1+3 Formalism Development

Part 1: General Relativity with a Linear Connection

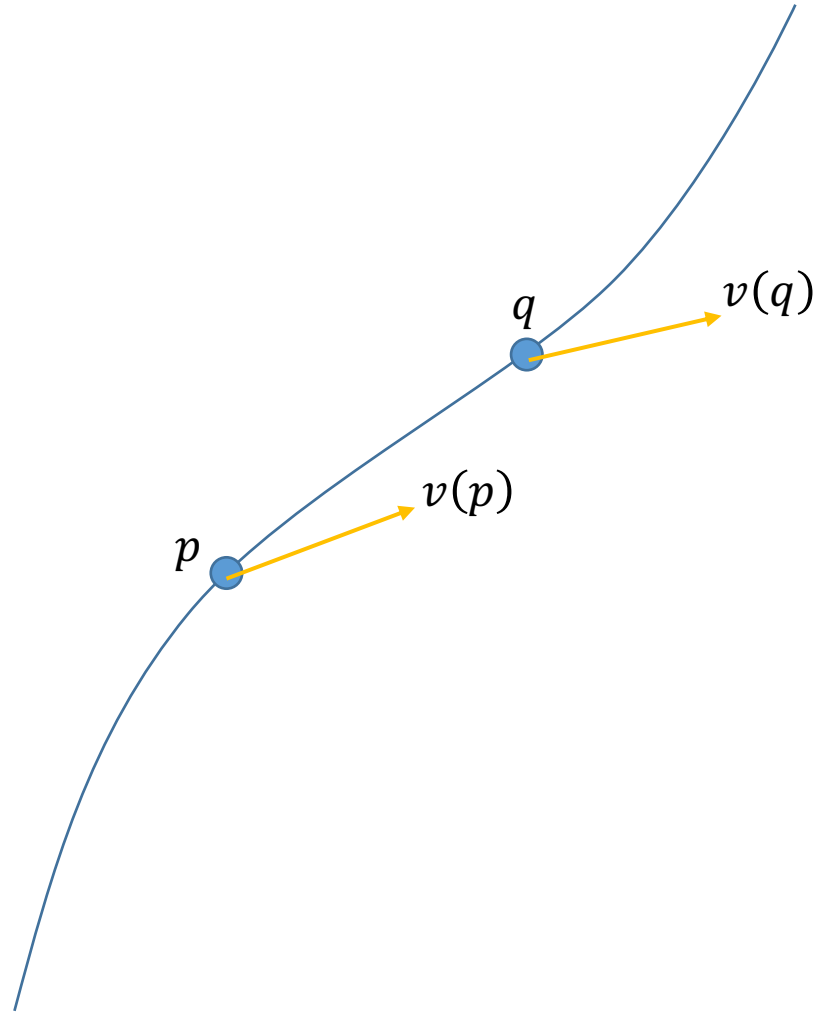
Linear Connection, Torsion, and Riemann Curvature

Abstract Index Notation

- Abstract indices: a, b, c, \dots
- Contraction
 - $v^a \omega_a = \mathbf{v}(\boldsymbol{\omega}) = \boldsymbol{\omega}(\mathbf{v}) = v^\mu \omega_\mu$
 - $T^{a\dots}{}_{b\dots} \omega_a \dots v^b \dots = \mathbf{T}(\boldsymbol{\omega}, \dots, \mathbf{v}, \dots) = T^{\mu\dots}{}_{\nu\dots} \omega_\mu \dots v^\nu \dots$
- Coordinate Basis
 - $\delta^\alpha{}_\beta = (dx^\alpha)_a (\partial/\partial x^\beta)^a$
 - $v^a = v^\mu (\partial/\partial x^\mu)^a$
 - $T^{a\dots}{}_{b\dots} = T^{\mu\dots}{}_{\nu\dots} (\partial/\partial x^\mu)^a \dots (dx^\nu)_b$
 - $\delta^a{}_b = (\partial/\partial x^\mu)^a (dx^\mu)_b$
 - $\omega_a = \omega_\mu (dx^\mu)_a$
- Pros
 - Clear distinction between tensors and components
 - Independence of coordinates and bases
 - Good readability

Differentiation of Vectors

- $\Delta \mathbf{v} = \mathbf{v}(q) - \mathbf{v}(p) = ?$

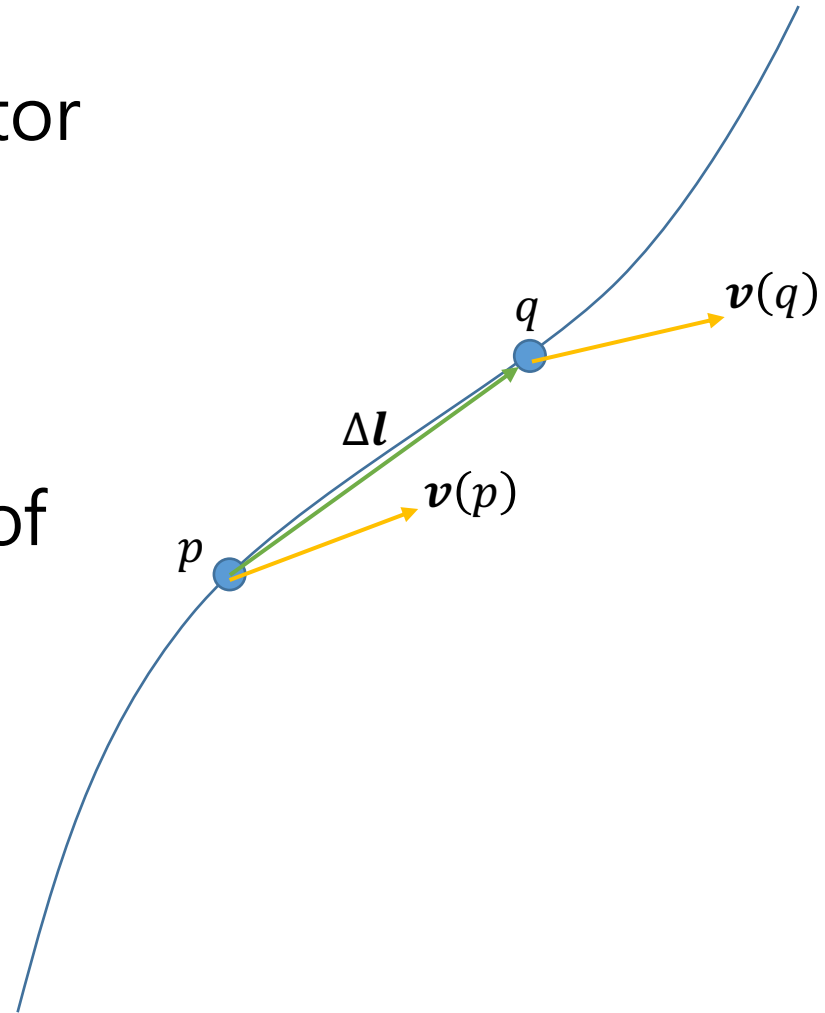


Linear (Affine) Connection

- 1. ∇ : vector field \times vector field \rightarrow vector field
 - $\nabla(\mathbf{u}, \mathbf{v})(\boldsymbol{\omega}) = (\nabla_{\mathbf{v}}\mathbf{u})(\boldsymbol{\omega}) = (\nabla\mathbf{u})(\boldsymbol{\omega}, \mathbf{v})$
 - $\omega_a(\nabla_{\mathbf{v}}\mathbf{u})^a = (\nabla\mathbf{u})^a_b \omega_a v^b = \omega_a v^b \nabla_b u^a$
- 2. slot 2 (Linearity over scalar field f)
 - $\nabla(\mathbf{u}, \mathbf{v} + f\mathbf{w}) = \nabla(\mathbf{u}, \mathbf{v}) + f\nabla(\mathbf{u}, \mathbf{w})$
 - $(v^b + fw^b)\nabla_b u^a = v^b \nabla_b u^a + fw^b \nabla_b u^a$
- 3. slot 1 (Leibniz Rule)
 - $\nabla(\mathbf{u} + f\mathbf{v}, \mathbf{w}) = \nabla(\mathbf{u}, \mathbf{w}) + f\nabla(\mathbf{v}, \mathbf{w}) + \mathbf{v}\mathbf{w}(f)$
 - $w^b \nabla_b(u + fv^a) = w^b \nabla_b w + fw^b \nabla_b v^a + v^a w^b (df)_b$

Parallel Transportation via Connection ∇

- $\Delta \mathbf{l}$: infinitesimal displacement vector from p to q
- $\Delta \mathbf{v} = \nabla(\mathbf{v}, \Delta \mathbf{l})$
- $(\Delta \mathbf{v})^a = (\Delta l)^b \nabla_b v^a$
- Freedom to choose $\Delta \mathbf{v}$ = Degree of freedom of connection



Extension of ∇ to any Type of Tensors

- 1. Gradient: $v^a \nabla_a f = \mathbf{v}(f) = v^a (df)_a$

- 2. Leibniz Rule: $\nabla(TU) = T\nabla U + U\nabla T$

- $v^a \nabla_b \omega_a = \nabla_b (\omega_a v^a) - \omega_a \nabla_b v^a$

- $\omega_{a_1}^1 \cdots \omega_{a_k}^k v_1^{b_1} \cdots v_l^{b_l} \nabla_c T^{a_1 \cdots a_k}_{b_1 \cdots b_l} =$
 $\nabla_c (T^{a_1 \cdots a_k}_{b_1 \cdots b_l} \omega_{a_1}^1 \cdots \omega_{a_k}^k v_1^{b_1} \cdots v_l^{b_l})$

$$- \sum_{i=1}^k T^{a_1 \cdots a_i \cdots a_k}_{b_1 \cdots b_l} \omega_{a_1}^1 \cdots \nabla_c \omega_{a_i}^i \cdots \omega_{a_k}^k v_1^{b_1} \cdots v_l^{b_l}$$

$$- \sum_{i=1}^l T^{a_1 \cdots a_k}_{b_1 \cdots b_i \cdots b_l} \omega_{a_1}^1 \cdots \omega_{a_k}^k v_1^{b_1} \cdots \nabla_c v_i^{b_i} \cdots v_l^{b_l}$$

Torsion Tensor

- Definition
 - $\mathbf{T}(\mathbf{u}, \mathbf{v}) \equiv \nabla_{\mathbf{u}}\mathbf{v} - \nabla_{\mathbf{v}}\mathbf{u} - [\mathbf{u}, \mathbf{v}]$
 - $[T(u, v)]^a \equiv u^b \nabla_b v^a - v^b \nabla_b u^a - [u, v]^a = u^a v^b (\nabla_b \nabla_a - \nabla_a \nabla_b) f$
- Anti Symmetricity
 - $\mathbf{T}(\mathbf{u}, \mathbf{v}) = -\mathbf{T}(\mathbf{v}, \mathbf{u})$
- Bilinearity over scalar field f
 - $\mathbf{T}(f\mathbf{u} + \mathbf{t}, \mathbf{v}) = f\mathbf{T}(\mathbf{u}, \mathbf{v}) + \mathbf{T}(\mathbf{t}, \mathbf{v})$
 - $[T(u, v)]^a = T^a_{bc} u^b v^c$
- Compact Form
 - $T^a_{bc} \nabla_a f = -2\nabla_{[b} \nabla_{c]} f$

Riemann Curvature Tensor

- Definition

- $\mathbf{R}(\mathbf{u}, \mathbf{v})\mathbf{w} = \nabla_{\mathbf{u}}\nabla_{\mathbf{v}}\mathbf{w} - \nabla_{\mathbf{v}}\nabla_{\mathbf{u}}\mathbf{w} - \nabla_{[\mathbf{u}, \mathbf{v}]}\mathbf{w}$

- $[R(u, v)w]^a \equiv u^c \nabla_c (v^d \nabla_d w^a) - v^d \nabla_d (u^c \nabla_c w^a) - [u, v]^b \nabla_b w^a$
 $= u^c v^d [(\nabla_c \nabla_d - \nabla_d \nabla_c)w^a - T^b_{cd} \nabla_b w^a]$

- Anti Symmetricity

- $\mathbf{R}(\mathbf{u}, \mathbf{v})\mathbf{w} = -\mathbf{R}(\mathbf{v}, \mathbf{u})\mathbf{w}$

- Bilinearity over scalar field f

- $\mathbf{R}(f\mathbf{u} + \mathbf{t}, \mathbf{v})\mathbf{w} = f\mathbf{R}(\mathbf{u}, \mathbf{v})\mathbf{w} + \mathbf{R}(\mathbf{t}, \mathbf{v})\mathbf{w}$

- $\mathbf{R}(\mathbf{u}, \mathbf{v})(f\mathbf{w} + \mathbf{t}) = f\mathbf{R}(\mathbf{u}, \mathbf{v})\mathbf{w} + \mathbf{R}(\mathbf{u}, \mathbf{v})\mathbf{t}$

- $[R(u, v)w]^a = R^a_{bcd} w^b u^c v^d$

- Compact Form

- $R^a_{bcd} w^b = 2\nabla_{[c} \nabla_{d]} w^a + T^b_{cd} \nabla_b w^a$

Useful Formula

- Commutation of Connection

- $(\nabla_c \nabla_d - \nabla_d \nabla_c) S^a_b = S^e_b R^a_{ecd} - S^a_e R^e_{bcd} - T^e_{cd} \nabla_e S^a_b$

- Lie Derivatives

- $(\mathcal{L}_u S)^a_b = u^c \nabla_c S^a_b + S^c_b (T^a_{cd} u^d - \nabla_c u^a) - S^a_c (T^c_{bd} u^d - \nabla_b u^c)$

- Exterior Derivatives

- $(d\omega)_{a_1 \dots a_{p+1}} = (p+1) \left(\nabla_{[a_1} \omega_{a_2 \dots a_{p+1}]} + \frac{1}{2} p \omega_{b[a_1 \dots a_{p-1}} T^b_{a_p a_{p+1}} \right)$

- Bianchi Identities

- $R^a_{[bcd]} = \nabla_{[b} T^a_{cd]} + T^a_{e[b} T^e_{cd]}$

- $\nabla_{[e} R^a_{|b|cd]} = -R^a_{bf[e} T^f_{cd]}$

Metric Connection

- Definition

- $\nabla_c g_{ab} = 0$ (# of eqs = $4 \times 10 = 40$)

- Properties

- $\nabla_e \epsilon_{abcd} = 0$

- $0 = \nabla_e (\epsilon^{abcd} \epsilon_{abcd}) = 2\epsilon^{abcd} \nabla_e \epsilon_{abcd}$

- $R_{(ab)cd} = 0$

- $0 = 2\nabla_{[c} \nabla_{d]} g_{ab} = -g_{eb} R^e{}_{acd} - g_{ae} R^e{}_{bcd}$

Torsion Free Connection

- Definition
 - $T^a{}_{bc} = 0$ (# of eqs = $4 \times 6 = 24$)
- Commutation of Connection
 - $(\nabla_c \nabla_d - \nabla_d \nabla_c)S^a{}_b = S^e{}_b R^a{}_{ecd} - S^a{}_e R^e{}_{bcd}$
- Lie Derivatives
 - $(\mathcal{L}_u S)^a{}_b = u^c \nabla_c S^a{}_b - S^c{}_b \nabla_c u^a + S^a{}_c \nabla_b u^c$
- Exterior Derivatives
 - $(d\omega)_{a_1 \dots a_{p+1}} = (p + 1) \nabla_{[a_1} \omega_{a_2 \dots a_{p+1}]}$
- Bianchi Identities
 - $R^a{}_{[bcd]} = 0$
 - $\nabla_{[e} R^a{}_{|b|cd]} = 0$

Levi-Civita Connection

- Definition

- $\nabla_c g_{ab} = 0$

- $T^a_{bc} = 0$

- # of eqs = $4 \times 10 + 4 \times 6 = 64$

- Properties

- $R_{abcd} = R_{cdab}$

- General relativity is described by the Levi-Civita connection.

Connection adapted to a Basis

- Basis and its Dual
 - $(e^\alpha)_a (e_\beta)^a = \delta^\alpha_\beta$ $(e_\mu)^a (e^\mu)_b = \delta^a_b$
- Definition
 - $\bar{\nabla}_b (e_\alpha)^a = 0$ implies $\bar{\nabla}_b (e^\alpha)_a = 0$
- Components of Covariant Derivatives
 - $\bar{\nabla}_c S^a_b = (e_\mu)^a (e^\nu)_b (e^\lambda)_c e_\lambda (S^\mu_\nu)$
- Torsion
 - $\bar{T}^a_{bc} = -[e_\mu, e_\nu]^a (e^\mu)_b (e^\nu)_c$
- Riemann Curvature
 - $\bar{R}^a_{bcd} = 0$
- Commutation of Connection
 - $(\bar{\nabla}_c \bar{\nabla}_d - \bar{\nabla}_d \bar{\nabla}_c) S^a_b = -T^e_{cd} \bar{\nabla}_e S^a_b$

Connection adapted to a Tetrad

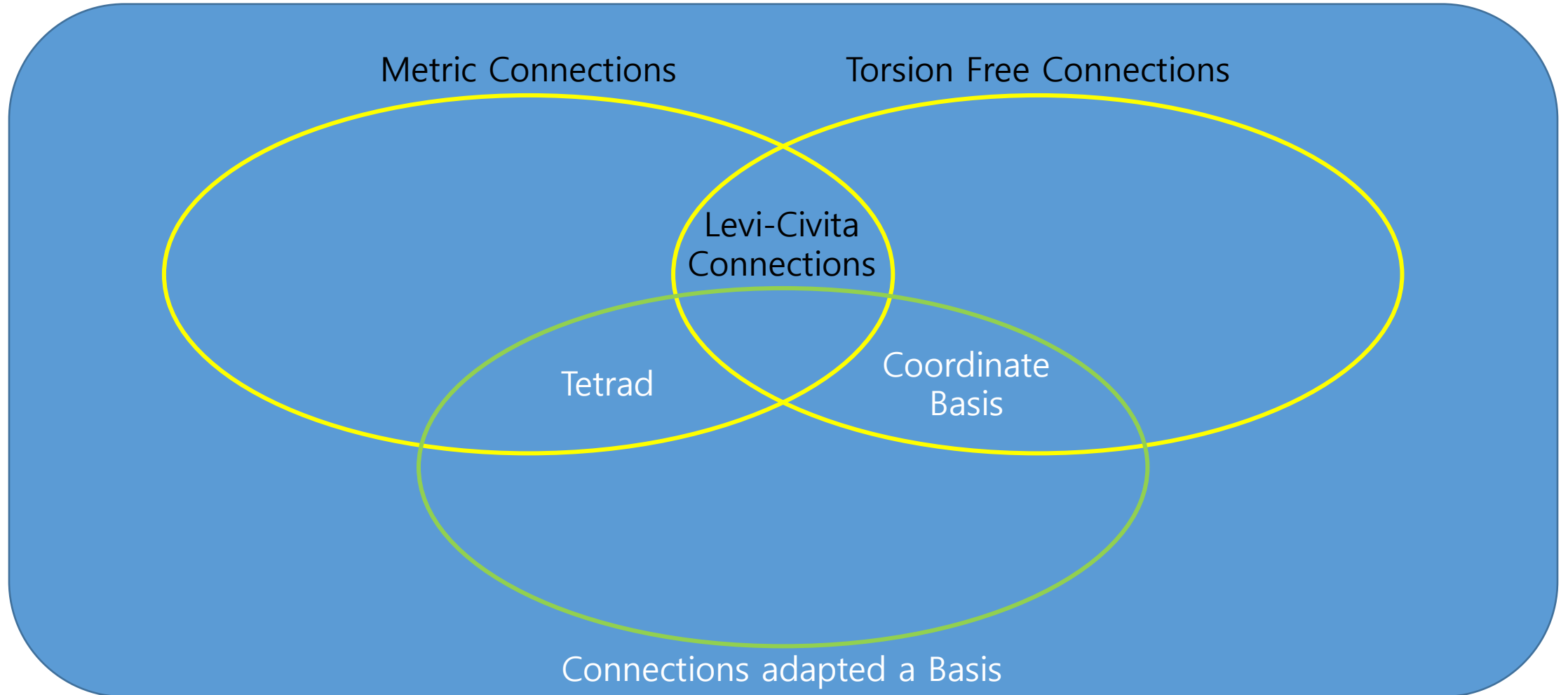
- Tetrad (Orthonormal basis)
 - $g_{ab}(e_\alpha)^a(e_\beta)^b = \eta_{\alpha\beta}$
- Metric connection
 - $\bar{\nabla}_c g_{ab} = (e^\mu)_a(e^\nu)_b(e^\lambda)_c e_\lambda(\eta_{\mu\nu}) = 0$
 - $\bar{\nabla}_e \epsilon_{abcd} = 0$
- We should keep the torsion \bar{T}^a_{bc}

Connection adapted to a Coordinate Basis

- Torsion Free Connection
 - $\bar{T}^a_{bc} = -[\partial/\partial x^\mu, \partial/\partial x^\nu]^a (e^\mu)_b (e^\nu)_c = 0$
- Conventionally
 - $\bar{\nabla} \rightarrow \partial$

Summary

Linear Connections



Relation between Two Connections

Connection Relation Tensor

- Definition

- $(\tilde{\nabla}_c - \nabla_c)S^a_b = S^d_b C^a_{dc} - S^a_d C^d_{bc}$

- Degree of Freedom for a Connection

- Given ∇ , C completely determines $\tilde{\nabla}$

- D.O.F of $\tilde{\nabla} = \text{D.O.F of } C = 4 \times 4 \times 4 = 64$

Relation of Torsions and Riemann Curvatures

- Torsions

- $(\tilde{T} - T)^a{}_{bc} = -2C^a{}_{[bc]}$

- Riemann Curvatures

- $(\tilde{R} - R)^a{}_{bcd} = 2\nabla_{[c}C^a{}_{|b|d]} + 2C^a{}_{e[c}C^e{}_{|b|d]} + C^a{}_{be}T^e{}_{cd}$

- Bianchi Identities

- $(\tilde{R} - R)^a{}_{[bcd]} = -2\nabla_{[b}C^a{}_{cd]} - 2C^a{}_{e[b}C^e{}_{cd]} + T^e{}_{[bc}C^a{}_{d]e}$

- $(\tilde{\nabla}\tilde{R} - \nabla R)^a{}_{b[cde]} = \text{not yet...}$

Determination of \mathcal{C}

- $$\mathcal{C}_{abc} = -\frac{1}{2} \left\{ (\tilde{T} - T)_{abc} + (\tilde{T} - T)_{bca} - (\tilde{T} - T)_{cab} + (\tilde{\nabla} - \nabla)_c g_{ab} + (\tilde{\nabla} - \nabla)_b g_{ca} - (\tilde{\nabla} - \nabla)_a g_{bc} \right\}$$
- Given ∇ , $\tilde{\nabla}g$ and \tilde{T} completely determines \mathcal{C}
- D.O.F of $\mathcal{C} = 64 = \text{D.O.F of } \tilde{\nabla}g + \text{D.O.F of } \tilde{T} = 40 + 24$
- Levi-Civita connection is unique because we impose
 - $\nabla_c g_{ab} = 0$ # of Eqs = 40
 - $T^a_{bc} = 0$ # of Eqs = 24

Levi-Civita Connection written by Another

- ∇ : Levi-Civita connection
- $\tilde{\nabla}$: Another connection
- $(\nabla - \tilde{\nabla})_c S^a_b = S^d_b C^a_{dc} - S^a_d C^d_{bc}$
- $\tilde{T}^a_{bc} = 2C^a_{[bc]}$
- $C_{abc} = \frac{1}{2}(\tilde{T}_{abc} + \tilde{T}_{bca} - \tilde{T}_{cab} + \tilde{\nabla}_c g_{ab} + \tilde{\nabla}_b g_{ca} - \tilde{\nabla}_a g_{bc})$
- $(R - \tilde{R})^a_{bcd} = 2\tilde{\nabla}_{[c} C^a_{|b|d]} + 2C^a_{e[c} C^e_{|b|d]} + 2C^a_{be} C^e_{[cd]}$

Examples

We will apply it to developing 1+3 formalism.

- Written by Metric Connection

- $C_{abc} = \frac{1}{2}(\tilde{T}_{abc} + \tilde{T}_{bca} - \tilde{T}_{cab})$

- $C_{(ab)c} = 0$

- Written by Torsion Free Connection

- $C^a{}_{[bc]} = 0$

- $C_{abc} = \frac{1}{2}(\tilde{\nabla}_c g_{ab} + \tilde{\nabla}_b g_{ca} - \tilde{\nabla}_a g_{bc})$

- $(R - \tilde{R})^a{}_{bcd} = 2\tilde{\nabla}_{[c} C^a{}_{|b|d]} + 2C^a{}_{e[c} C^e{}_{|b|d]}$

Levi-Civita Connection written by Connection adapted to a Basis

- Conventionally,
 - $\mathcal{C} \rightarrow \Gamma$
- ∇ : Levi-Civita connection
- $\bar{\nabla}$: Connection adapted to a basis
- $(\nabla - \bar{\nabla})_c S^a_b = S^d_b \Gamma^a_{dc} - S^a_d \Gamma^d_{bc}$
- $\nabla_b (e_\alpha)^a = (e_\alpha)^c \Gamma^a_{cb}$ $\nabla_b (e^\alpha)_a = -(e^\alpha)_c \Gamma^c_{ab}$
- $\bar{T}^a_{bc} = 2\Gamma^a_{[bc]} = -[e_\mu, e_\nu]^a (e^\mu)_b (e^\nu)_c$
- $\Gamma_{abc} = \frac{1}{2} (\bar{T}_{abc} + \bar{T}_{bca} - \bar{T}_{cab} + \bar{\nabla}_c g_{ab} + \bar{\nabla}_b g_{ca} - \bar{\nabla}_a g_{bc})$
- $R^a_{bcd} = 2\bar{\nabla}_{[c} \Gamma^a_{|b|d]} + 2\Gamma^a_{e[c} \Gamma^e_{|b|d]} + 2\Gamma^a_{be} \Gamma^e_{[cd]}$

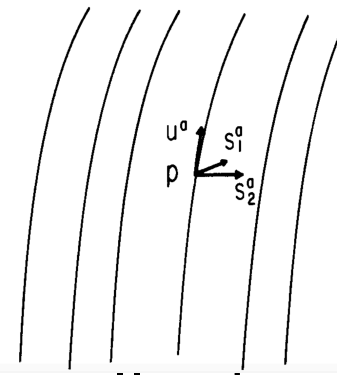
Examples

- Adapted to a tetrad
 - $\Gamma_{abc} = \frac{1}{2}(\bar{T}_{abc} + \bar{T}_{bca} - \bar{T}_{cab})$
 - is the Ricci rotation
 - $\Gamma_{(ab)c} = 0$
- Adapted to a coordinate basis
 - $\Gamma_{a[bc]} = 0$
 - $\Gamma_{abc} = \frac{1}{2}(\partial_c g_{ab} + \partial_b g_{ca} - \partial_a g_{bc})$
 - $R^a{}_{bcd} = 2\partial_{[c}\Gamma^a{}_{|b|d]} + 2\Gamma^a{}_{e[c}\Gamma^e{}_{|b|d]}$

Part 2: 1 + 3 Formalism Development

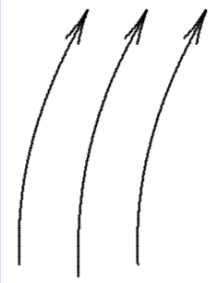
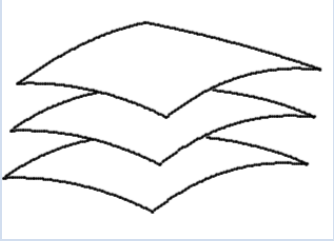
Introduction

Motivation



- In theoretical astrophysics, matter is usually described by perfect fluid which ignores heat transfer and viscosity.
- The perfect fluid provides a congruence of timelike integral curves on spacetime.
- We assume only existence of the timelike congruence for general applicability. Spacetime may not be globally hyperbolic.
- We introduce a time-space splitting formalism with respect to the congruence, i.e. 1+3 formalism.
- 1+3 formalism is applicable to Lagrangian perturbation theory.
- Because we don't have any assumption for the background spacetime, it is applicable to relativistic star, black hole and universe.

Comparison between 1+3 and 3+1

	1+3 Formalism	3+1 Formalism
Given Structure	 <p>u^a : unit tangent vector</p>	 <p>n^a : unit normal vector</p>
Covariant Derivatives	$\nabla_b u_a = -A_a u_b + \frac{1}{3} \Theta \gamma_{ab} + \Sigma_{ab} + \Omega_{ab}$	$\nabla_b n_a = -A_a n_b + K_{ab}$

When $\omega_{ab} = 0$, 1+3 formalism reduces to 3+1 formalism.

Time-Space Splitting

Parallel and Orthogonal Projection

- u^a : unit tangent to the congruence ($g_{ab}u^a u^b = -1$)

- $$V^a = v^a - (-u_b v^b)u^a$$

$$= (\delta^a_b + u^a u_b)v^b$$

$$= \gamma^a_b v^b$$

- Time-space splitting of tensors

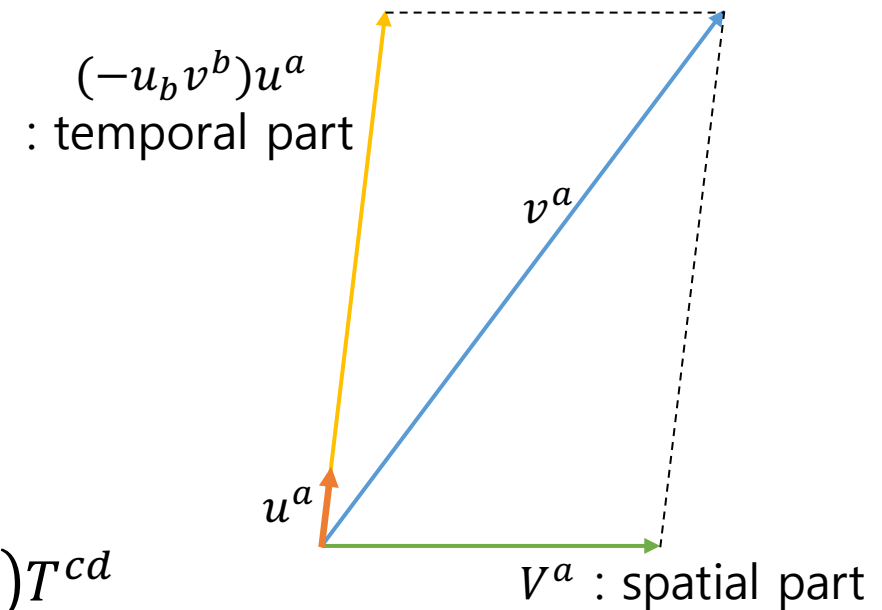
- $v^a = (-u_b v^b)u^a + \gamma^a_b v^b$

- $$T^{ab} = (u_c u_d T^{cd})u^a u^b + u^a (-u_c \gamma^b_d T^{cd})$$

$$+ (-\gamma^a_c u_d T^{cd})u^b + \gamma^a_c \gamma^b_d T^{cd}$$

- Notation for convenience

- $\perp (T^{ab}) \equiv \gamma^a_c \gamma^b_d T^{cd} \quad \parallel (T^{ab}) \equiv (-u^a u_c)(-u^b u_d)T^{cd}$



Splitting of Einstein Equation

- $T_{ab} = \rho u_a u_b + u_a P_b + P_a u_b + p \gamma_{ab} + S_{ab}$
 - Spatial: $P_a u^a = 0$ $S_{ab} u^a = 0$
 - Traceless: $S_{ab} g^{ab} = 0$
- $T = -\rho + 3p$
- Let $8\pi G = 1$
- $R_{ab} = T_{ab} - \frac{1}{2} g_{ab} T$
 $= \bar{\rho} u_a u_b + u_a P_b + P_a u_b + \bar{p} \gamma_{ab} + S_{ab}$
- Where
 - $\bar{\rho} = \frac{1}{2}(\rho + 3p)$ $\bar{p} = \frac{1}{2}(\rho - p)$

Splitting of Weyl Curvature

- C^{ab}_{cd} : Weyl curvature of Levi-Civita connection associated with spacetime metric g

- $$C^{ab}_{cd} = 4u^{[a}u_{[c}E^{b]}_{d]} + 2u^{[a}H^{b]e}\epsilon_{ecd} + 2u_{[c}H_{d]e}\epsilon^{eab} + 4\gamma^{[a}_{[c}E^{b]}_{d]}$$

- Where

- $\epsilon_{abc} = u^d \epsilon_{dabc}$

- $E^a_c = C^{ab}_{cd} u_b u^d$

- $H_{ec} = \frac{1}{2} \epsilon_{eab} C^{ab}_{cd} u^d$

$$E_{[ab]} = 0$$

$$E_{ab} u^a = 0$$

$$E_{ab} g^{ab} = 0$$

$$H_{[ab]} = 0$$

$$H_{ab} u^a = 0$$

$$H_{ab} g^{ab} = 0$$

Splitting of Riemann Curvature

- $R^{ab}{}_{cd}$: Riemann curvature of Levi-Civita connection associated with spacetime metric g
- $$R^{ab}{}_{cd} = C^{ab}{}_{cd} + 2\delta^{[a}{}_{[c}R^{b]}{}_{d]} - \frac{1}{3}R\delta^{[a}{}_{[c}\delta^{b]}{}_{d]}$$

$$= 4u^{[a}u_{]c} \left(E^{b]}{}_{d]} + \frac{1}{3}\bar{\rho}\gamma^{b]}{}_{d]} - \frac{1}{2}S^{b]}{}_{d]} \right)$$

$$+ 2u^{[a} \left(H^{b]}{}_{e}\epsilon_{ecd} - \gamma^{b]}{}_{[c}P_{d]} \right) + 2u_{[c} \left(H_{d]}{}_{e}\epsilon^{eab} - \gamma^{[a}{}_{d]}P^{b]} \right)$$

$$+ 4\gamma^{[a}{}_{[c} \left(E^{b]}{}_{d]} + \frac{1}{12}(\bar{\rho} + 3\bar{p})\gamma^{b]}{}_{d]} + \frac{1}{2}S^{b]}{}_{d]} \right)$$